List of Contents

Volume 12 Number 1 **March 1996**

A. Sharon	1	Editorial
S. Chan, M. Munro and **A. Fahim**	3	Accuracy–speed relationships of a robotic filament winding cell
C. R. Liu and **S. Mittal**	15	Single-step superfinish hard machining: feasibility and feasible cutting conditions
Z. Shiller, H. Chang and **V. Wong**	29	The practical implementation of time-optimal control for robotic manipulators
B. Shirinzadeh	41	A CAD-based hierarchical approach to interference detection among fixture modules in a reconfigurable fixturing system
A. N. Poo, K. B. Lim and **Y. X. Ma**	55	Application of discrete learning control to a robotic manipulator
J. M. Schimmels and **S. Huang**	65	A passive mechanism that improves robotic positioning through compliance and constraint
R. Boudreau, S. Darenfed and **E. Biden**	73	Application of time series and polynomial learning networks to robot trajectory error control
C. T. Culbreth, M. Miller and **P. O'Grady**	81	A concurrent engineering system to support flexible automation in furniture production
J. Scholliers and **H. Van Brussel**	93	Design and off-line programming of a robotic tape winding cell
M. Prinz, H.-C. Liu, B. O. Nnaji and **T. Lueth**	99	From CAD-based kinematic modeling to automated robot programming
M. Rybski, M. Shoham and **G. Grossman**	111	Robotic manipulators based on inflatable structures
	121	Announcements
	123	*PatentsAlert*

Volume 12 Number 2 **June 1996**

P. M. Pelagagge, G. Cardarelli and **M. Palumbo**	125	Some criteria to help the experimental setup of assembly cells with cooperating robots
M. M. Marefat and **L. Wu**	135	Purposeful gazing and vergence control for active vision
L. Mangialardi, G. Mantriota and **A. Trentadue**	157	A three-dimensional criterion for the determination of optimal grip points
H. Zhuang and **Z. S. Roth**	169	A note on singularities of the MCPC model
L. Ferrarini	173	Hierarchical multi-layer CAD system for systematic design of complex logic controllers

Y. Edan and **S. Y. Nof**	185	Graphic-based analysis of robot motion economy principles
S. Demey, H. Van Brussel and **H. Derache**	195	Determining set-ups for mechanical workpieces
	207	Calendar

Volume 12 Number 3 **September 1996**

R. Colbaugh, K. Glass and **H. Seraji**	209	Adaptive tracking control of manipulators: theory and experiments
J. Zhang, B. Chuah, E. Cheung and **Z. Deng**	217	Information modeling for manufacturing systems: a case study
G. Cardarelli, P. M. Pelagagge and **A. Granito**	227	Performance analysis of automated interbay material-handling and storage systems for large Wafer Fab
N. Dhayagude, Z. Gao and **F. Mrad**	235	Fuzzy logic control of automated screw fastening
J. Howell and **R. C. Young**	243	Reasoning about correlation-based inspection of small-batch-manufactured objects
J. Xiao and **R. A. Volz**	251	Constrained accelerated-feedback control for robot motion
T. Furukawa, D. C. Rye, M. W. M. G. Dissanayake and **A. J. Barratt**	261	Automated polishing of an unknown three-dimensional surface
T.-K. Peng and **A. J. C. Trappey**	271	CAD-integrated engineering-data-management system for spring design
	283	Erratum
	285	*PatentsALERT*

Volume 12 Number 4 **December 1996**

W. S. Newman, B. B. Mathewson, Y. Zheng and **S. Choi**	293	A novel selective-area gripper for layered assembly of laminated objects
E. Dermatas, A. Nearchou and **N. Aspragathos**	303	Error-back-propagation solution to the inverse kinematic problem of redundant manipulators
M. A. Rodrigues and **Y. F. Li A. Granito**	311	Dynamic systems modelling and development of robotic applications in a visual programming environment
M. Gülesin	321	Intermediate part modelling in a process planning and fixturing system
C.-P. Hwang and **C.-S. Ho**	329	A knowledge-based task-level programming and execution environment for robots

J. Zaytoon 353 Specification and design of logic controllers for automated manufacturing systems

367 Calendar

369 *PatentsALERT*

i Volume Contents and Author Index for Volume 12, 1996